

# Limitations of Threat Modeling in Adversarial Machine Learning

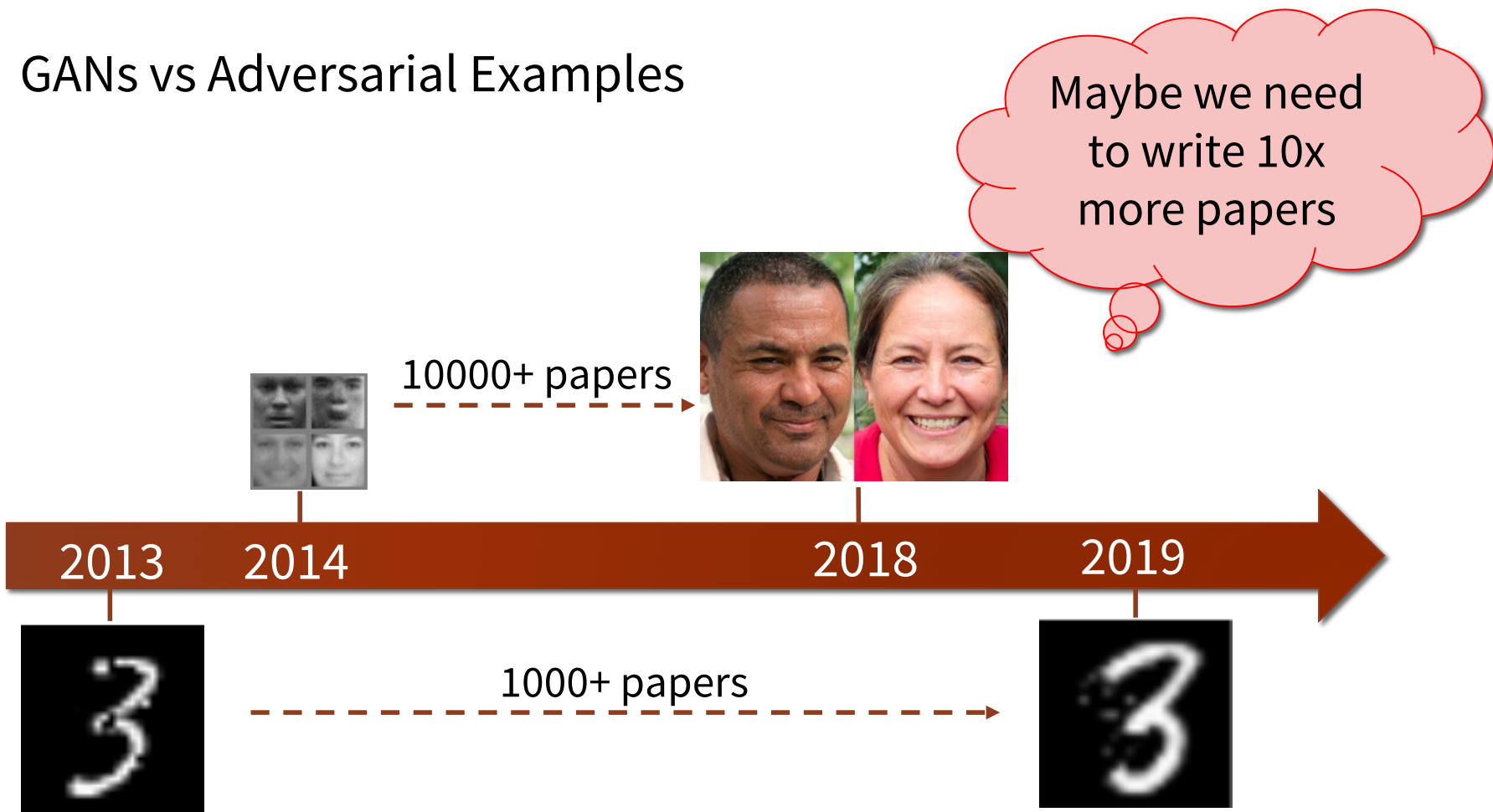
Florian Tramèr

EPFL, December 19<sup>th</sup> 2019

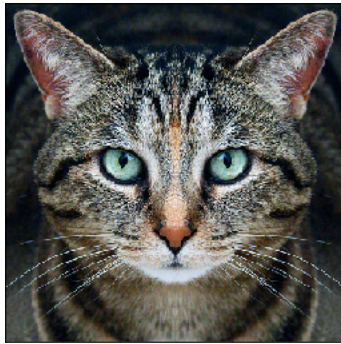
Based on joint work with Jens Behrmann, Dan Boneh, Nicholas Carlini, Pascal Dupré, Jörn-Henrik Jacobsen, Nicolas Papernot, Giancarlo Pellegrino, Gili Rusak

# The state of adversarial machine learning

## GANs vs Adversarial Examples

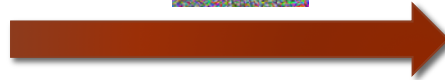
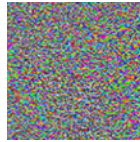


# Adversarial examples



88% Tabby Cat

+



99% Guacamole

Biggio et al., 2014  
Szegedy et al., 2014  
Goodfellow et al., 2015  
Athalye, 2017

## How?

- Training  $\Rightarrow$  “tweak model parameters such that  $f(\text{cat image}) = \textit{cat}$ ”
- Attacking  $\Rightarrow$  “tweak input pixels such that  $f(\text{cat image}) = \textit{guacamole}$ ”

# The bleak state of adversarial examples



A screenshot of a tweet from Elon Musk. The tweet text is "Never trust cynics, as they excuse their own bad deeds by telling themselves everyone does it". The tweet is dated 10:41 PM on Dec 18, 2019, and was posted from the iPhone app. It has 12.5K retweets and 91.1K likes. The profile picture shows a rocket launch, and the name "Elon Musk" is followed by a verified badge and the handle "@elonmusk". A dropdown arrow is visible in the top right corner of the tweet box.

 **Elon Musk**   
@elonmusk

Never trust cynics, as they excuse their own bad deeds by telling themselves everyone does it

10:41 PM · Dec 18, 2019 · [Twitter for iPhone](#)

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**12.5K** Retweets   **91.1K** Likes



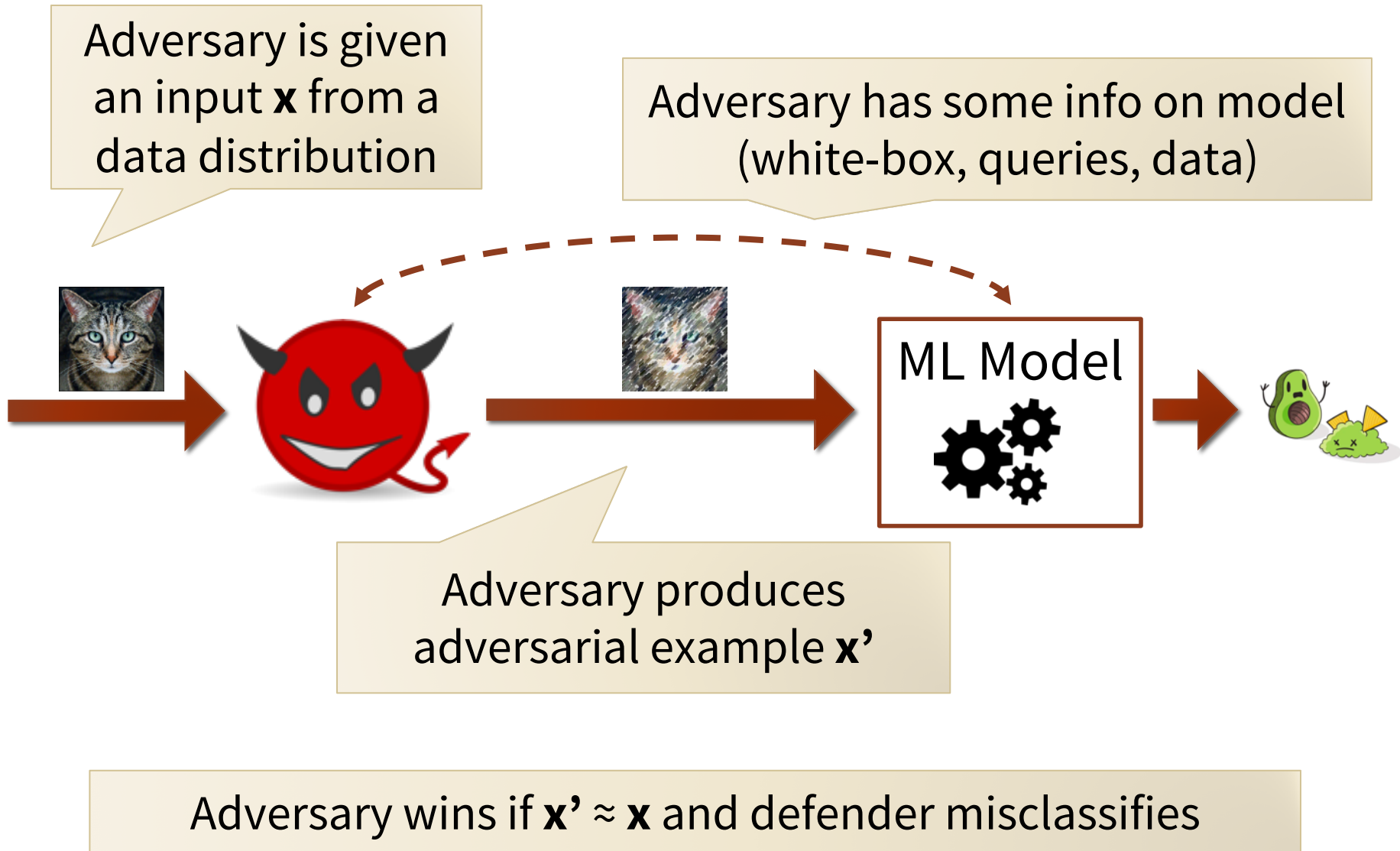
# The bleak state of adversarial examples

- Most papers study a “toy” problem  
Solving it is not useful per se, but maybe we’ll find new insights or techniques
- Going beyond this toy problem (even slightly) is hard
- Overfitting to the toy problem happens and is harmful
- The “non-toy” version of the problem is not actually that relevant for computer security  
(except for ad-blocking)

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# The standard game [Gilmer et al. 2018]



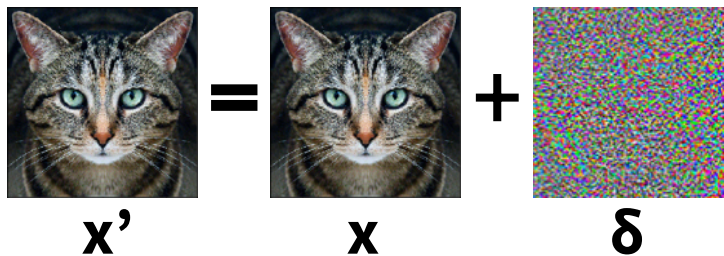
# Relaxing and formalizing the game

How do we define  $\mathbf{x}' \approx \mathbf{x}$  ?

- “Semantics” preserving, fully imperceptible?

Conservative approximations [Goodfellow et al. 2015]

- Consider noise that is clearly semantics-preserving

E.g.,  where  $\|\boldsymbol{\delta}\|_{\infty} = \max \delta_i \leq \epsilon$

- Robustness to this noise is *necessary* but not *sufficient*
- **Even this “toy” version of the game is hard, so let’s focus on this first**

# Progress on the toy game

- **Many** broken defenses [Carlini & Wagner 2017, Athalye et al. 2018]
- **Adversarial Training** [Szegedy et al., 2014, Madry et al., 2018]  
⇒ For each training input  $(\mathbf{x}, y)$ , train on worst-case adversarial input

$$\operatorname{argmax}_{\|\boldsymbol{\delta}\|_{\infty} \leq \epsilon} \operatorname{Loss}(f(\mathbf{x} + \boldsymbol{\delta}), y)$$

- **Certified Defenses**  
[Hein & Andriushchenko 2017, Raghunathan et al., 2018, Wong & Kolter 2018]

## Progress on the toy game

- **Robustness to noise of small  $l_p$  norm is a “toy” problem**
  - ⇒ For each training input  $(x, y)$ , train on worst-case adversarial input
- **Solving this problem is not useful per se, unless it teaches us new insights**
- **Solving this problem does not give us “secure ML”**

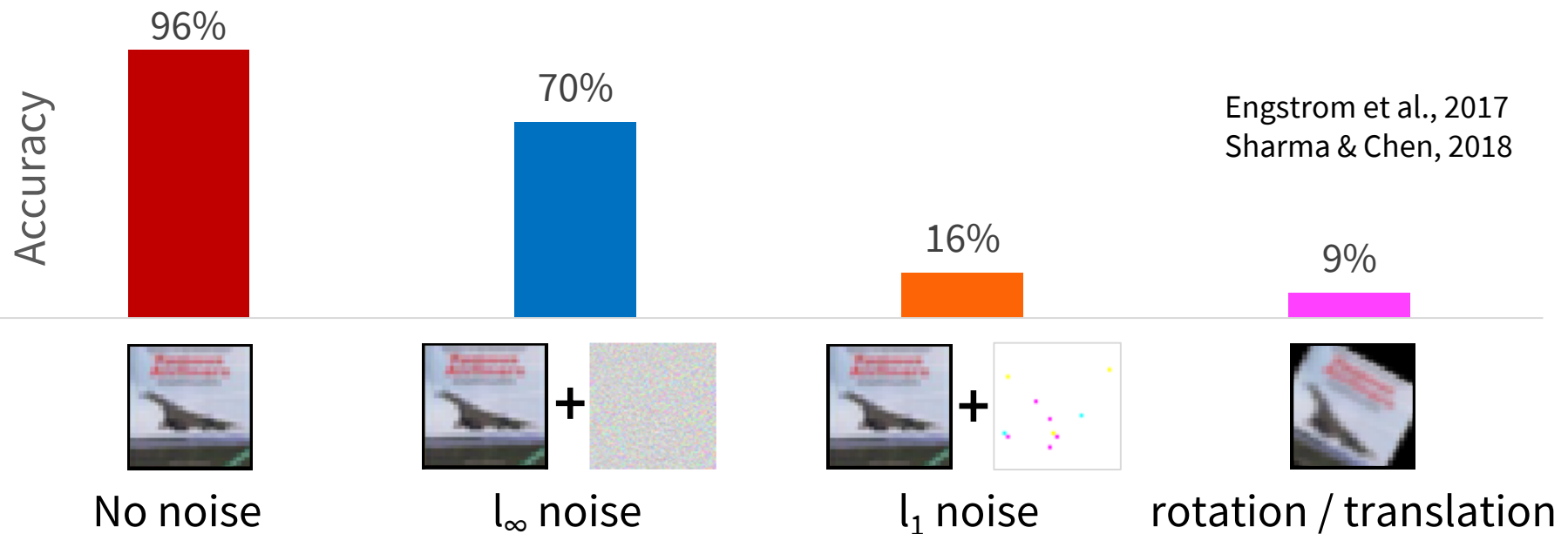
# Outline

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Solving it is not useful per se, but maybe we’ll find new insights or techniques
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# Beyond the toy game

Issue: defenses do not generalize

Example: training against  $l_\infty$ -bounded noise on CIFAR10



Robustness to one type can **increase** vulnerability to others



# Robustness to more perturbation types

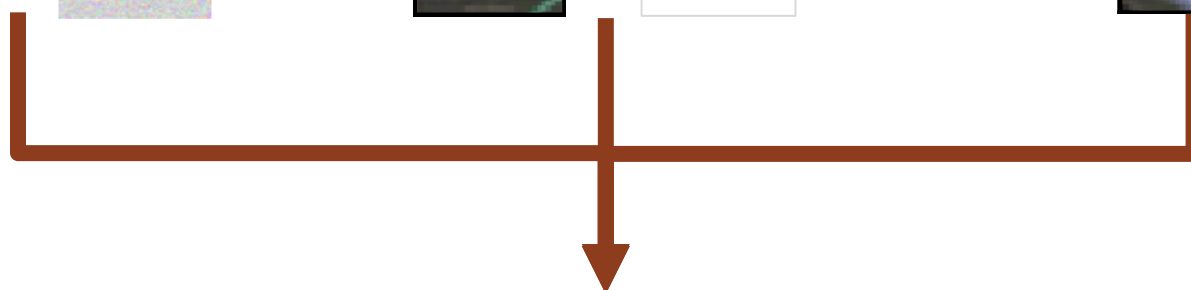
$$S_1 = \{\delta: \|\delta\|_\infty \leq \varepsilon_\infty\}$$



$$S_2 = \{\delta: \|\delta\|_1 \leq \varepsilon_1\}$$



$$S_3 = \{\delta: \text{«small rotation»}\}$$



$$S = S_1 \cup S_2 \cup S_3$$

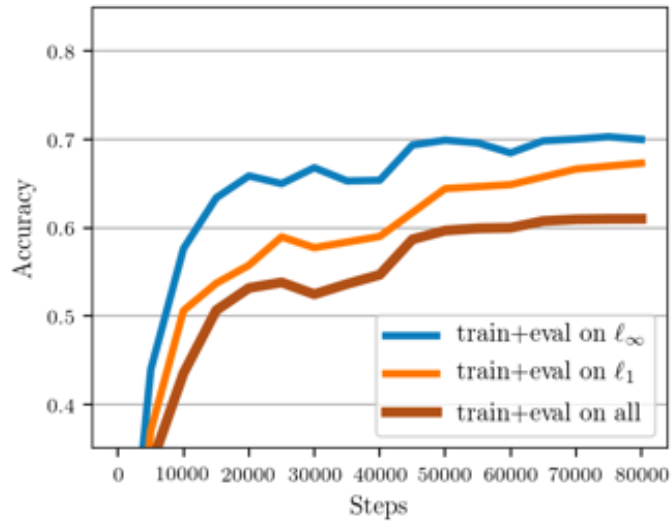
- Pick worst-case adversarial example from **S**
- Train the model on that example

# Empirical multi-perturbation robustness

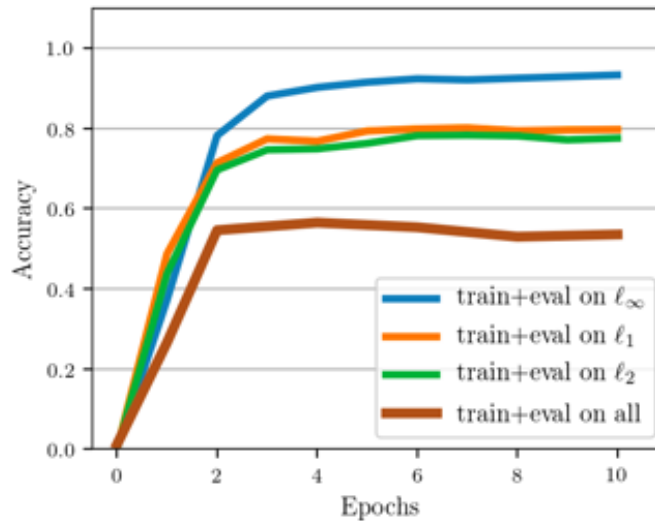
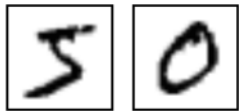
CIFAR10:

ship

dog



MNIST:



# Empirical multi-perturbation robustness

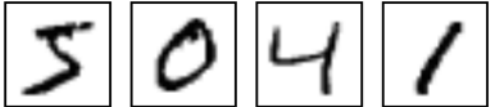
**Current defenses scale poorly to multiple perturbations**

**We also prove that a robustness tradeoff is *inherent* for simple data distributions**

# Outline

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# Invariance adversarial examples

  $\in \{0, 1\}^{784}$

Highest robustness claims in the literature:

- 80% robust accuracy to  $l_0 = 30$



- **Certified** 85% robust accuracy to  $l_\infty = 0.4$



natural



$l_\infty \leq 0.4$



$l_0 \leq 30$



**Robustness  
considered  
harmful**

# Invariance adversarial examples

5 0 4 1  $\in \{0, 1\}^{784}$

Highest robustness claims in the literature:

- 80% robust accuracy to  $l_0 = 30$
- Certified 85% robust accuracy to  $l_\infty = 0.4$

**We do not even know how to set the “right” bounds for the toy problem**

natural

0 1 2 7 0

$l_\infty \leq 0.4$

0 7 2 7 0

$l_0 \leq 30$

9 0 7 7 0

robustness  
considered  
harmful

# Adversarial examples are hard!

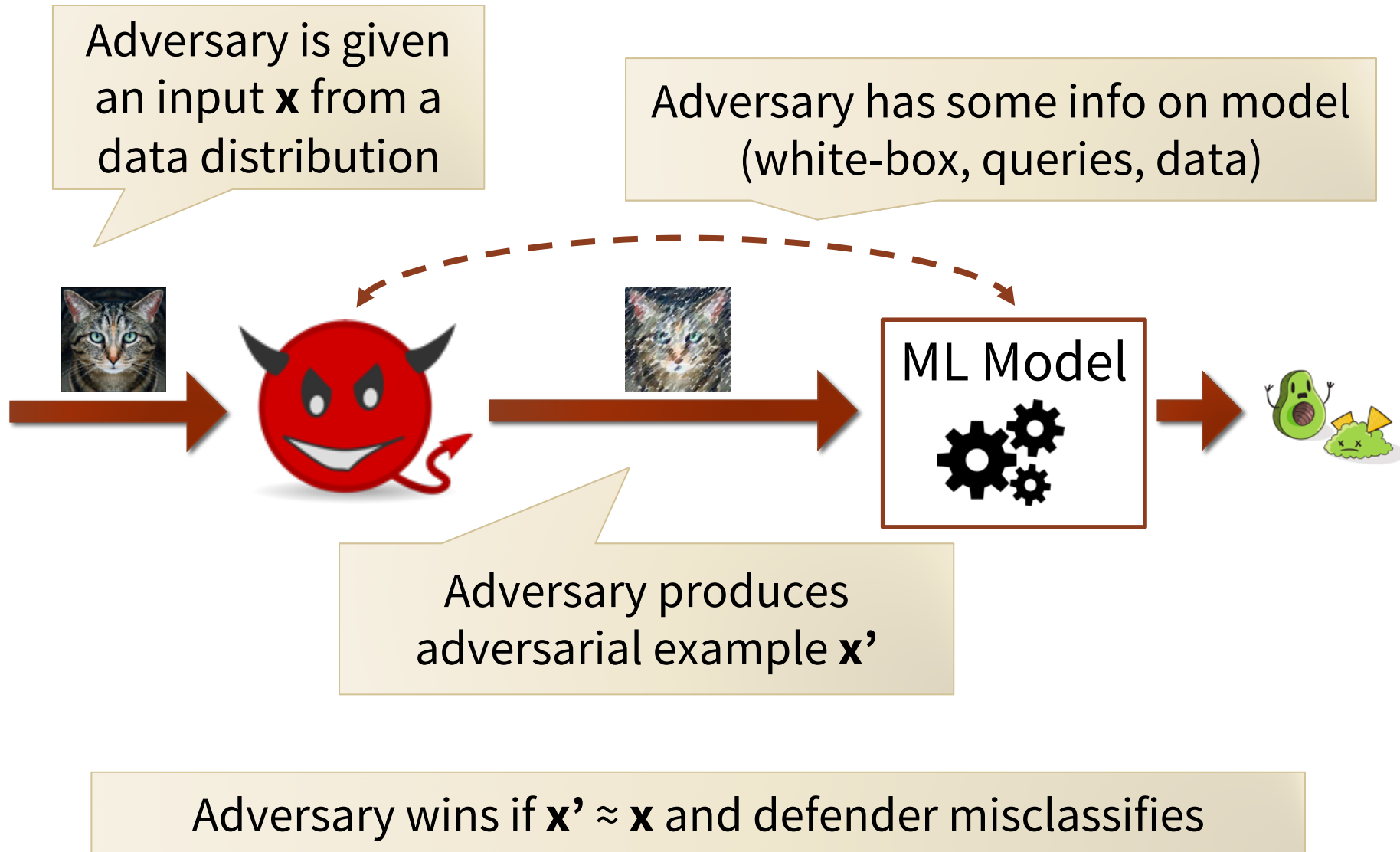
- Most current work: small progress on the relaxed game
- Moving towards the standard game is hard
  - Even robustness to 2-3 perturbations types is tricky
  - **How would we even enumerate all necessary perturbations?**
- Over-optimizing robustness is harmful
  - **How do we set the right bounds?**
- **We need a formal model of perceptual similarity**
  - But then we've probably solved all of computer vision anyhow...

# Outline

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# Recap on the standard game



## Recap on the standard game

Adversary is given an input  $x$  from a data distribution

Adversary has some info on model (white-box, queries, data)

**There are very few settings where this game captures a relevant threat model**

Adversary produces adversarial example  $x'$

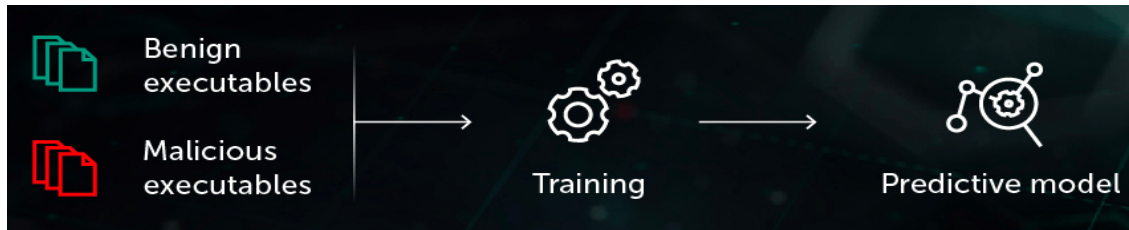
Adversary wins if  $x' \approx x$  and defender misclassifies

# ML in security/safety critical environments



Fool self-driving cars' street-sign detection

[Eykholt et al. 2017+2018]



Evade malware detection

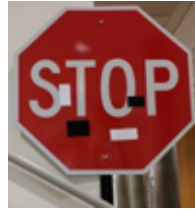
[Grosse et al. 2018]

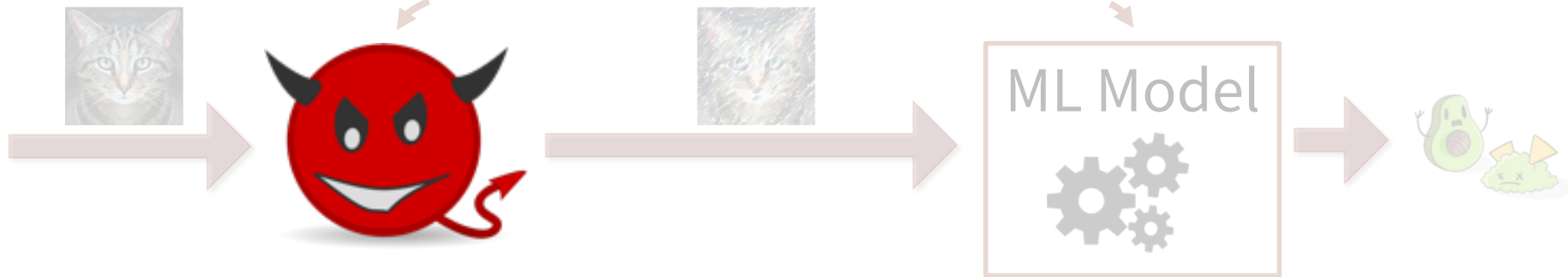


Fool visual ad-blockers

[T et al. 2019]

# Is the standard game relevant?





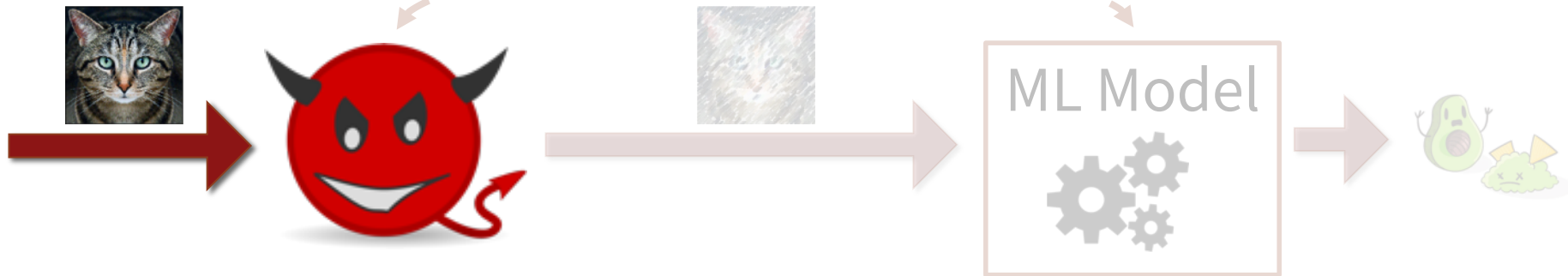
# Is the standard game relevant?



**Is there an adversary?**



Adversary is given an input  $x$  from a data distribution



# Is the standard game relevant?

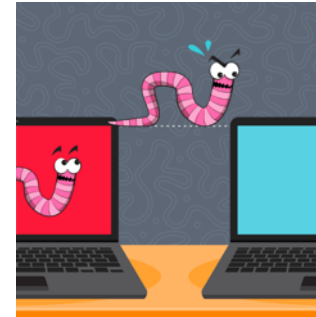


Is there an adversary?



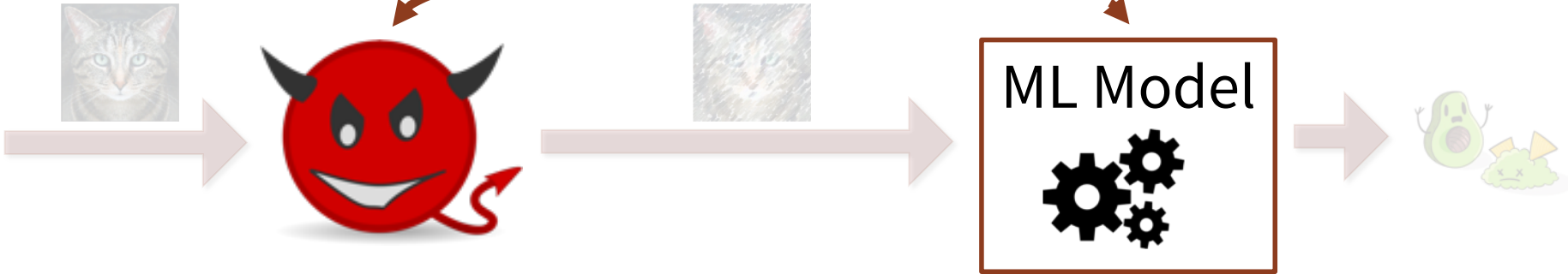
**Is average-case success important?**

(Adv cannot choose which inputs to attack)





Adversary has some info on model  
(white-box, queries, data)



# Is the standard game relevant?



Is there an adversary?

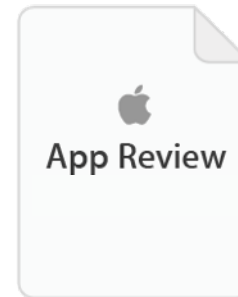


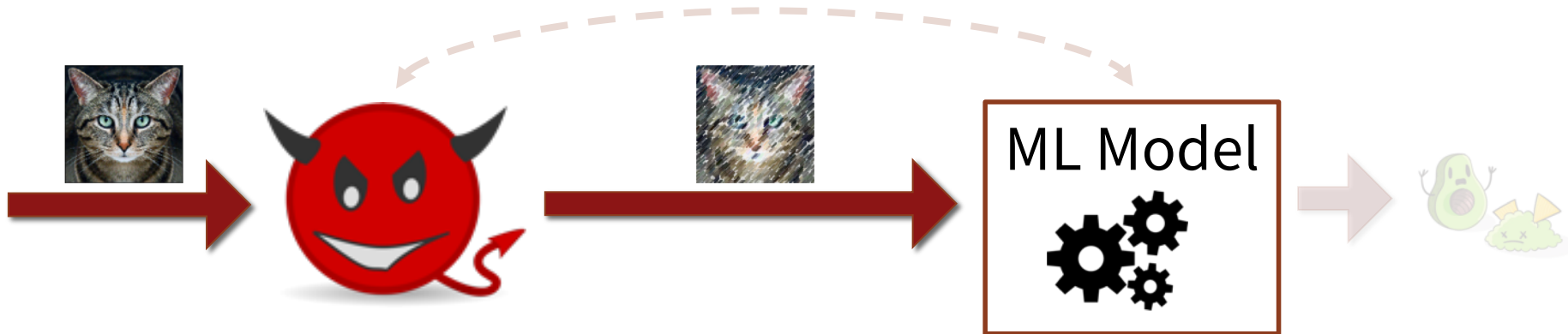
Average-case success?



**Model access?**

(white-box, queries, data)





Adversary wins if  $x' \approx x$  and defender misclassifies

# Is the standard game relevant?



Is there an adversary?



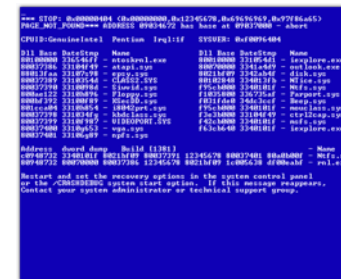
Average-case success?



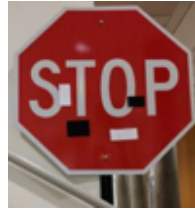
Access to model?



**Should attacks preserve semantics?  
(or be fully imperceptible)**



# Is the standard game relevant?



Is there an adversary?



Average-case success?



Access to model?



Semantics-preserving perturbations?



**Unless the answer to all these questions is Yes, the standard game of adversarial examples is not the right threat model**

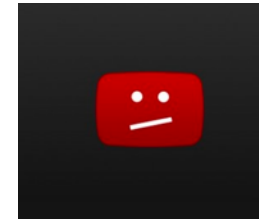
# Where else could the game be relevant?



**Anti-phishing**

## Technology

Inside YouTube's struggles to shut down video of the New Zealand shooting – and the humans who outsmarted its systems

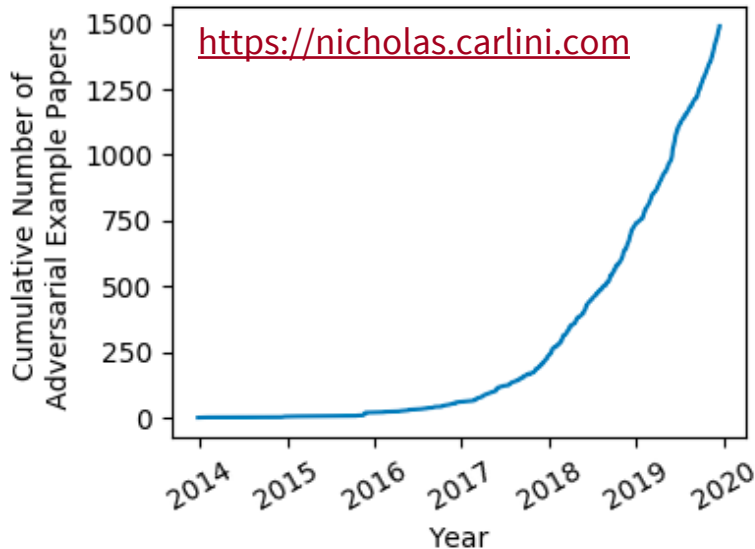


**Content takedown**

**Common theme: human-in-the-loop!**

(Adversary wants to fool ML without disrupting UX)

# Steps forward



Most of these papers consider the relaxed game

Progress on this game is not useful *per se*

For safety-critical ML (e.g., self-driving):

- There is no adversary (but worst-case analysis can be useful)
- Consider “natural” perturbations (fog, snow, lighting, angles, etc.)

For *real* security-critical ML (e.g., malware detection):

- Attackers often care about breaking in once (analyzing static classifiers is not very useful)
- Security through obscurity (restricted model access) “works” in practice



Maybe we do not need 10x more papers... just the right ones



# Backup slides

# The multi-perturbation robustness trade-off

If there exist models with high robust accuracy for perturbation sets  $S_1, S_2, \dots, S_n$ , does there **exist** a model robust to perturbations from  $\bigcup_{i=1}^n S_i$ ?

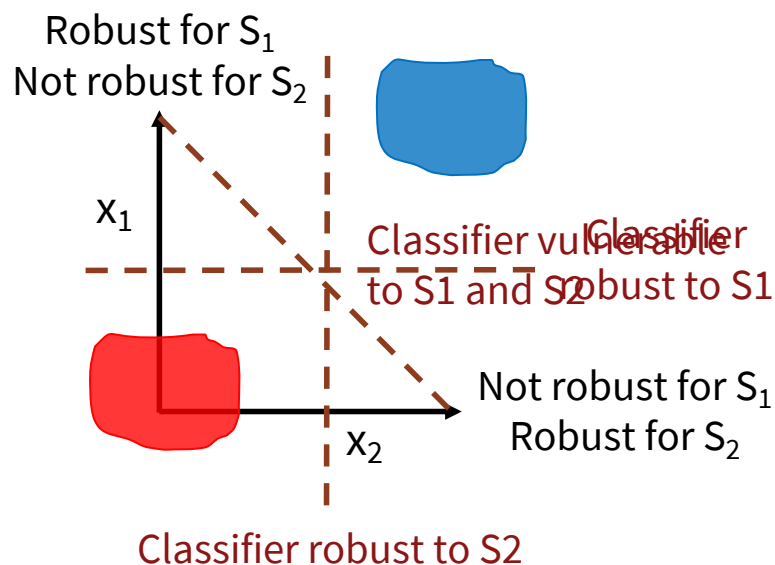
Answer: in general, NO!

There exist “mutually exclusive perturbations” (MEPs)

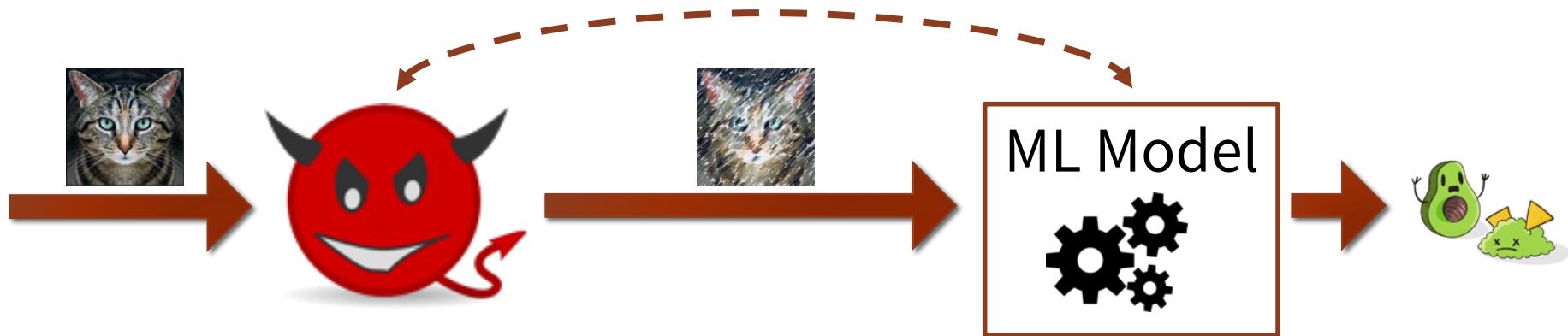
(robustness to  $S_1$  implies vulnerability to  $S_2$  and vice-versa)

Formally, we show that for a simple Gaussian binary classification task:

- $l_1$  and  $l_\infty$  noise are MEPs
- $l_\infty$  noise and spatial perturbations are MEPs



# The standard game [Gilmer et al. 2018]



1. Adversary is given input  $\mathbf{x}$  from some data distribution
2. Adversary gets some information on model:
  - Access to model parameters (white-box)
  - Query access
  - Access to similar training data
3. Adversary outputs an adversarial example  $\mathbf{x}'$
4. Defender classifies  $\mathbf{x}'$

Adversary wins if  $\mathbf{x}' \approx \mathbf{x}$  and defender misclassifies